

# Global Types for Dynamic Checking of Protocol Conformance of Multi-Agent Systems

**Davide Ancona**, Viviana Mascardi and Matteo Barbieri

Università di Genova

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# Outline

- 1 Research topics, aims and motivations
- 2 Background on multi-agent systems
- 3 Global types
- 4 Expressivity of global types
- 5 Enhanced global types
- 6 References (a very short selected list)

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# Research topics and aims

## Work Package 2

### Negotiation: Transactions, Reversibility and Compensations

#### Task 2.4: Contracts and Compliance

#### **Session types for multi-agent systems**

#### Aims

- Dynamic checking of protocol conformance in multi-agent systems
- Expressive formalisms for specifying complex protocols
- Protocol specifications as first-order values
- Integration with static checking, gradual typing (possible future directions)

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  - ▶ Verification of complex protocols
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  - ▶ Complex protocols should be expressible in a succinct way
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  - ▶ Agents can send and receive protocol specifications
  - ▶ Interesting feature for adaptivity through behavioral types (WP1, T1.3), and run-time monitoring for global correctness (WP5, T5.3)



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  - ▶ Interesting feature for adaptivity through behavioral types (WP1, T1.3), and run-time monitoring for global correctness (WP5, T5.3)
- Static checking
  - ▶ Stronger guarantees
  - ▶ More challenging, more conservative analysis

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- Behavioral types
  - ▶ Global types: specify agent interaction globally
  - ▶ Session types: specify agent interaction locally

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- Behavioral types
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- Contractive regular types (guarded cyclic terms)
  - ▶ Natural support for recursion
  - ▶ Coinductive interpretation: infinite interactions are allowed
- Trace-based interpretation
  - ▶ Defined in terms of a labeled transition system
  - ▶ Dynamic checking obtained through the implementation of the transition relation

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# Multi-agent systems (MASs)

- industrial-strength technology for integrating and coordinating heterogeneous systems
- intrinsically distributed nature, asynchronous message passing
- agent-oriented programming languages are typically dynamically typed

- AgentSpeak: a logic-based agent-oriented programming language, based on the belief-desire-intention (BDI) software model
- Jason: open source interpreter for an extended version of AgentSpeak, supporting a Prolog-like language for specifying agents behavior
- communication model: speech-act based, with performatives (a.k.a. illocutionary forces)

# Sending actions in Jason

```
.send(recipient,performative,content)
```

- *recipient*: the *id* of the agent that will receive the message
- *performative*: specifies the semantics/aim of the message

**tell   untell   achieve   unachieve   tell-how  
untell-how   ask-if   ask-all   ask-how**

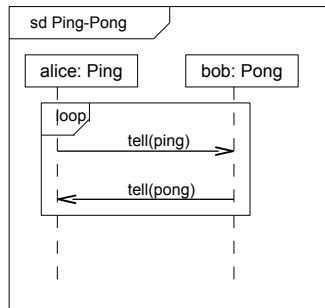
- *content*: a (possibly empty) set of atoms or plans



# Protocol specification for multi-agent systems

## Interaction diagrams in FIPA AUML

- specify the behavior of a system from a global point of view
- suitable for humans, but not for verification
- not expressive enough in some situations



[FIPA Modeling: Interaction Diagrams,

<http://www.auml.org/auml/documents/ID-03-07-02.pdf>]

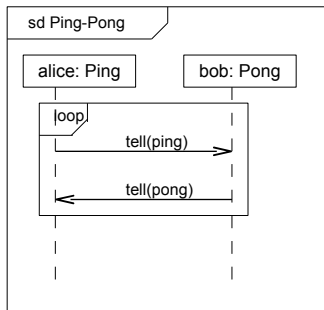
# Interpretation of protocol specification

## Protocol

set of (possibly infinite) sequences of sending actions

## Example: ping-pong protocol

```
msg(alice,bob,tell,ping) msg(bob,alice,tell,pong)  
msg(alice,bob,tell,ping) msg(bob,alice,tell,pong) ...
```



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# Protocols specified by global types

## Sending action types

Monadic predicates which define a set of valid sending actions

Example:

ping corresponds to `msg (alice, bob, tell, ping)`

pong corresponds to `msg (bob, alice, tell, pong)`

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## A global type for the ping-pong protocol

`PingPong = ping:pong:PingPong`

$\alpha:T$  means

any message action specified by the sending action type  $\alpha$ ,  
followed by any sequence specified by the global type  $T$

# Global types as Prolog cyclic terms

`PingPong` is a contractive regular type defined by a recursive syntactic equation

- Modern Prolog systems (and Jason as well) support cyclic terms (a.k.a. regular terms)
- Example: the unification problem

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PingPong = ping:pong:PingPong.
```

succeeds with the answer `PingPong = ping:pong:PingPong`

- Regular terms naturally support recursive types
- Regular Prolog terms: a very compact representation of protocol specifications through global types

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## Protocol specifications as first-class values

**Protocols can be easily manipulated and exchanged by agents**

# Constructors for global types

- $\lambda$ : *empty sequence* (denoting  $\{\epsilon\}$ )
- $\alpha:\tau$  *sequence constructor* (already seen)
- $\tau_1 + \tau_2$  *choice* (union)
- $\tau_1 | \tau_2$  *fork* (shuffle)
- $\tau_1 \cdot \tau_2$  *concat* (concatenation)



# Interpretation of global types

- $\llbracket \tau \rrbracket$  = set of finite/infinite sequences of sending actions determined by the transition relation
- Finite sequences are allowed if the final type  $\tau$  specifies a protocol that can terminate, that is,  $\epsilon(\tau)$  holds

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## Definition of $\epsilon(-)$

$$\begin{array}{ccc} (\epsilon\text{-seq}) \frac{}{\epsilon(\lambda)} & (\epsilon\text{-lchoice}) \frac{\epsilon(\tau_1)}{\epsilon(\tau_1 + \tau_2)} & (\epsilon\text{-rchoice}) \frac{\epsilon(\tau_2)}{\epsilon(\tau_1 + \tau_2)} \\ (\epsilon\text{-fork}) \frac{\epsilon(\tau_1) \quad \epsilon(\tau_2)}{\epsilon(\tau_1 | \tau_2)} & (\epsilon\text{-cat}) \frac{\epsilon(\tau_1) \quad \epsilon(\tau_2)}{\epsilon(\tau_1 \cdot \tau_2)} & \end{array}$$

**Example:**  $\llbracket \lambda + \text{ping} : \lambda \rrbracket = \{ \epsilon, \text{msg}(\text{alice}, \text{bob}, \text{tell}, \text{ping}) \}$

# Transition rules

## Simple version, unconstrained shuffle

$$\begin{array}{l} \text{(seq)} \frac{}{\alpha : \tau \xrightarrow{a} \tau} \quad a \in \alpha \\ \text{(choice-l)} \frac{\tau_1 \xrightarrow{a} \tau'_1}{\tau_1 + \tau_2 \xrightarrow{a} \tau'_1} \\ \text{(choice-r)} \frac{\tau_2 \xrightarrow{a} \tau'_2}{\tau_1 + \tau_2 \xrightarrow{a} \tau'_2} \\ \text{(fork-l)} \frac{\tau_1 \xrightarrow{a} \tau'_1}{\tau_1 | \tau_2 \xrightarrow{a} \tau'_1 | \tau_2} \\ \text{(fork-r)} \frac{\tau_2 \xrightarrow{a} \tau'_2}{\tau_1 | \tau_2 \xrightarrow{a} \tau_1 | \tau'_2} \\ \text{(cat-l)} \frac{\tau_1 \xrightarrow{a} \tau'_1}{\tau_1 \cdot \tau_2 \xrightarrow{a} \tau'_1 \cdot \tau_2} \\ \text{(cat-r)} \frac{\tau_2 \xrightarrow{a} \tau'_2}{\tau_1 \cdot \tau_2 \xrightarrow{a} \tau_1 \cdot \tau'_2} \quad \epsilon(\tau_1) \end{array}$$

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# Alternating bit protocol (ABP(4))

- A typical benchmark for testing expressivity (see DeniélouYoshida@ESOP2012)
- Infinite sequences of the following sending actions:
  - ▶ `msg(alice, bob, tell, msg1)` (sending action type `msg1`)
  - ▶ `msg(alice, bob, tell, msg2)` (sending action type `msg2`)
  - ▶ `msg(bob, alice, tell, ack1)` (sending action type `ack1`)
  - ▶ `msg(bob, alice, tell, ack2)` (sending action type `ack2`)

Required constraints (for all  $n$ ):

- $msg1_n < ack1_n < msg1_{n+1}$
- $msg2_n < ack2_n < msg2_{n+1}$
- $msg1_n < msg2_n < msg1_{n+1}$

$\alpha_n$  denotes the  $n$ -th occurrence of the sending action  $a$  of type  $\alpha$

# A global type specifying ABP(4)

## A first attempt

$$\text{WrongAltBit} = MA_1 | MA_2$$
$$MA_1 = \text{msg}_1 : \text{ack}_1 : MA_1$$
$$MA_2 = \text{msg}_2 : \text{ack}_2 : MA_2$$

- $\text{msg}_{1n} < \text{ack}_{1n} < \text{msg}_{1n+1}$
- $\text{msg}_{2n} < \text{ack}_{2n} < \text{msg}_{2n+1}$
- $\text{msg}_{1n} < \text{msg}_{2n} < \text{msg}_{1n+1}$

# A global type specifying ABP(4)

## A first attempt

$WrongAltBit = MA_1 | MA_2$

$MA_1 = msg_1:ack_1:MA_1$

$MA_2 = msg_2:ack_2:MA_2$

- $msg1_n < ack1_n < msg1_{n+1}$  **OK**
- $msg2_n < ack2_n < msg2_{n+1}$
- $msg1_n < msg2_n < msg1_{n+1}$

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$WrongAltBit = MA_1 | MA_2$

$MA_1 = msg_1:ack_1:MA_1$

$MA_2 = msg_2:ack_2:MA_2$

- $msg1_n < ack1_n < msg1_{n+1}$  **OK**
- $msg2_n < ack2_n < msg2_{n+1}$  **OK**
- $msg1_n < msg2_n < msg1_{n+1}$



# A global type specifying ABP(4)

## A first attempt

$WrongAltBit = MA_1 | MA_2$

$MA_1 = msg_1:ack_1:MA_1$

$MA_2 = msg_2:ack_2:MA_2$

- $msg1_n < ack1_n < msg1_{n+1}$  **OK**
- $msg2_n < ack2_n < msg2_{n+1}$  **OK**
- $msg1_n < msg2_n < msg1_{n+1}$  **NO**

# A global type specifying ABP(4)

## Correct type

$$AltBit_1 = msg_1 : M_2$$

$$AltBit_2 = msg_2 : M_1$$

$$M_1 = (msg_1 : A_2) + (ack_2 : AltBit_1)$$

$$A_1 = (ack_1 : M_1) + (ack_2 : ack_1 : AltBit_1)$$

$$M_2 = (msg_2 : A_1) + (ack_1 : AltBit_2)$$

$$A_2 = (ack_2 : M_2) + (ack_1 : ack_2 : AltBit_2)$$

## Problems:

- quite complex type, not very readable
- the complexity of the type grows exponentially with the number of messages

## A global type specifying ABP(6)

$$\mathit{AltBit}_3 = \mathit{msg}_1 : S_1$$

$$S_1 = (\mathit{msg}_2 : S_2) + (\mathit{ack}_1 : \mathit{msg}_2 : S_6)$$

$$S_2 = (\mathit{ack}_1 : S_6) + ((\mathit{ack}_2 : S_4) + (\mathit{msg}_3 : S_3))$$

$$S_3 = (\mathit{ack}_1 : S_7) + ((\mathit{ack}_2 : S_8) + (\mathit{ack}_3 : S_5))$$

$$S_4 = (\mathit{ack}_1 : \mathit{msg}_3 : \mathit{ack}_3 : \mathit{AltBit}_3) + (\mathit{msg}_3 : S_8)$$

$$S_5 = (\mathit{ack}_1 : \mathit{ack}_2 : \mathit{AltBit}_3) + (\mathit{ack}_2 : \mathit{ack}_1 : \mathit{AltBit}_3)$$

$$S_6 = (\mathit{msg}_3 : S_7) + (\mathit{ack}_2 : \mathit{msg}_3 : \mathit{ack}_3 : \mathit{AltBit}_3)$$

$$S_7 = (\mathit{ack}_3 : \mathit{ack}_2 : \mathit{AltBit}_3) + (\mathit{ack}_2 : \mathit{ack}_3 : \mathit{AltBit}_3)$$

$$S_8 = (\mathit{ack}_1 : \mathit{ack}_3 : \mathit{AltBit}_3) + (\mathit{ack}_3 : \mathit{ack}_1 : \mathit{AltBit}_3)$$

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# Constrained shuffle

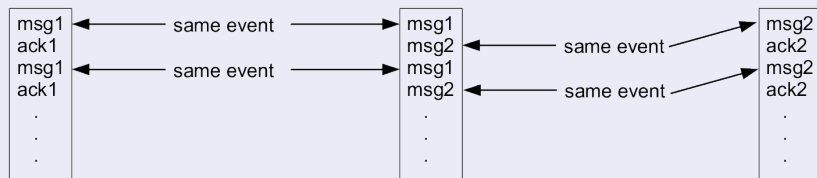
## Intuition

For every correct sequence  $s$  of ABP(4)

- $s$  restricted to  $msg_1$  and  $ack_1$  is in  $MA_1 = msg_1:ack_1:MA_1$
- $s$  restricted to  $msg_2$  and  $ack_2$  is in  $MA_2 = msg_2:ack_2:MA_2$
- $s$  restricted to  $msg_1$  and  $msg_2$  is in  $MM = msg_1:msg_2:MM$

But  $MA_1 | MA_2 | MM$  is not correct!

## Shuffle needs to be constrained



# Extended global types

- Constrained shuffle
- *Producer* sending action type  $\alpha^n$ : must be “consumed” by  $n$  consumer types ( $n \geq 0$ )
- *Consumer* sending action type  $\alpha$

An unconstrained shuffle contains just producer sending action types of shape  $\alpha^0$

# Transition rules (revisited)

## Extended version, constrained shuffle

$$\begin{array}{c}
 \text{(seq-prod)} \frac{}{0, \alpha^n : \tau \xrightarrow{a} \tau, n} \quad a \in \alpha \quad \text{(seq-cons)} \frac{}{n, \alpha : \tau \xrightarrow{a} \tau, n-1} \quad n > 0 \\
 a \in \alpha
 \end{array}$$

$$\text{(fork-both-l)} \frac{n_1, \tau_1 \xrightarrow{a} \tau'_1, n_2 \quad n_2, \tau_2 \xrightarrow{a} \tau'_2, n_3}{n_1, \tau_1 | \tau_2 \xrightarrow{a} \tau'_1 | \tau'_2, n_3} \quad n_2 > 0$$

$$\text{(fork-both-r)} \frac{n_1, \tau_2 \xrightarrow{a} \tau'_2, n_2 \quad n_2, \tau_1 \xrightarrow{a} \tau'_1, n_3}{n_1, \tau_1 | \tau_2 \xrightarrow{a} \tau'_1 | \tau'_2, n_3} \quad n_2 > 0$$

$$\text{(fork-l)} \frac{n_1, \tau_1 \xrightarrow{a} \tau'_1, n_2}{n_1, \tau_1 | \tau_2 \xrightarrow{a} \tau'_1 | \tau_2, n_2}$$

$$\text{(fork-r)} \frac{n_1, \tau_2 \xrightarrow{a} \tau'_2, n_2}{n_1, \tau_1 | \tau_2 \xrightarrow{a} \tau_1 | \tau'_2, n_2}$$

$$\text{(choice-l)} \frac{n_1, \tau_1 \xrightarrow{a} \tau'_1, n_2}{n_1, \tau_1 + \tau_2 \xrightarrow{a} \tau'_1, n_2}$$

$$\text{(choice-r)} \frac{n_1, \tau_2 \xrightarrow{a} \tau'_2}{n_1, \tau_1 + \tau_2 \xrightarrow{a} \tau'_2, n_2}$$

$$\text{(cat-l)} \frac{n_1, \tau_1 \xrightarrow{a} \tau'_1, n_2}{n_1, \tau_1 \cdot \tau_2 \xrightarrow{a} \tau'_1 \cdot \tau_2, n_2}$$

$$\text{(cat-r)} \frac{n_1, \tau_2 \xrightarrow{a} \tau'_2, n_2}{n_1, \tau_1 \cdot \tau_2 \xrightarrow{a} \tau_1 \cdot \tau'_2, n_2} \quad \epsilon(\tau_1)$$

# Alternating bit protocol (revisited)

## ABP(4)

$$\begin{aligned}AB &= MA'_1 | MA'_2 | MM \\ MA'_1 &= msg_1^1 : ack_1^0 : MA'_1 \\ MA'_2 &= msg_2^1 : ack_2^0 : MA'_2 \\ MM &= msg_1 : msg_2 : MM\end{aligned}$$

## ABP(6)

$$\begin{aligned}AB_3 &= MA_1 | MA_2 | MA_3 | MM_3 \\ MA_1 &= msg_1^1 : ack_1^0 : MA_1 \\ MA_2 &= msg_2^1 : ack_2^0 : MA_2 \\ MA_3 &= msg_3^1 : ack_3^0 : MA_3 \\ MM_3 &= msg_1 : msg_2 : msg_3 : MM_3\end{aligned}$$



# A comparison

## ABP(4): proposed solution in DeniélouYoshida@ESOP2012

$$\begin{aligned} \mathbf{G}_{ABP} &= \text{def } \mathbf{x}_0 &= \mathbf{x}_1 \mid \mathbf{x}_2 \\ \mathbf{x}_1 + \mathbf{x}_3 &= \mathbf{x}_4 \\ \mathbf{x}_2 + \mathbf{x}_5 &= \mathbf{x}_6 \\ \mathbf{x}_4 &= \text{Alice} \rightarrow \text{Bob} : \mathit{Msg}_1 \langle \text{string} \rangle ; \mathbf{x}_7 \\ \mathbf{x}_7 &= \mathbf{x}_8 \mid \mathbf{x}_9 \\ \mathbf{x}_8 &= \text{Bob} \rightarrow \text{Alice} : \mathit{Ack}_1 \langle \text{unit} \rangle ; \mathbf{x}_{10} \\ \mathbf{x}_6 \mid \mathbf{x}_9 &= \mathbf{x}_{11} \\ \mathbf{x}_{11} &= \text{Alice} \rightarrow \text{Bob} : \mathit{Msg}_2 \langle \text{string} \rangle ; \mathbf{x}_{12} \\ \mathbf{x}_{12} &= \mathbf{x}_{13} \mid \mathbf{x}_{14} \\ \mathbf{x}_{13} &= \text{Bob} \rightarrow \text{Alice} : \mathit{Ack}_2 \langle \text{unit} \rangle ; \mathbf{x}_5 \\ \mathbf{x}_{10} \mid \mathbf{x}_{14} &= \mathbf{x}_3 \text{ in } \mathbf{x}_0 \end{aligned}$$

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D. Ancona, M. Barbieri, and V. Mascardi.

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**Thank you for your attention...**

**...questions?**

